## Math 231 Midterm 1 Review Sheet, 9/30/2025

The first midterm will be on Thursday 10/9 during your usual lecture time. It has four problems (one being a few multiple-choice questions) and is 90 minutes long. You are allowed to use a basic calculator but it won't be something you need. Here is a list of the topics that you are advised to study:

- Vectors in  $\mathbb{R}^n$  and their components; vector addition and scalar multiplication; dot product and its basic properties; norm and distance; the triangle and Cauchy-Schwarz inequalities; the angle between two vectors; orthogonal vectors; orthogonal projection of one vector onto another.
- Solving systems of linear equations by elimination, i.e., by reducing the associated augmented matrix to a row echelon form; leading and free variables; every consistent (in particular, homogeneous) system with fewer equations than unknowns has infinitely many solutions.
- Linear combinations of vectors; the span of a set of vectors; geometric view of the span in  $\mathbb{R}^2$  and  $\mathbb{R}^3$ ; linear dependence versus independence.
- Place the vectors  $\mathbf{v}_1, \dots, \mathbf{v}_k$  in  $\mathbb{R}^n$  as the *columns* of an  $n \times k$  matrix A. Then

$$x_1$$
**v**<sub>1</sub> + ··· +  $x_k$ **v**<sub>k</sub> = **b**  $\iff$   $x_1, ..., x_k$  is a solution of  $[A|\mathbf{b}]$ .

Thus, we have the following two tests:

Span Test:

$$\mathbf{b} \in \operatorname{span}\{\mathbf{v}_1, \dots, \mathbf{v}_k\} \iff [A|\mathbf{b}] \text{ has a solution.}$$

Dependence Test:

$$\mathbf{v}_1, \dots, \mathbf{v}_k$$
 dependent  $\iff [A|\mathbf{0}]$  has infinitely many solutions.

As a result, every collection of more than n vectors in  $\mathbb{R}^n$  must be dependent.

- Addition and multiplication of matrices; the transpose of a matrix; symmetric matrices.
- The inverse of a matrix; if A is invertible, the system  $A\mathbf{x} = \mathbf{b}$  has the unique solution  $\mathbf{x} = A^{-1}\mathbf{b}$ ; the formula for the inverse of a 2 × 2 matrix:

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \Longrightarrow A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}.$$

- Elementary matrices; if an elementary row operation applied to  $I_n$  gives the elementary matrix E, then the same operation applied to any  $n \times n$  matrix A gives the matrix EA.
- Finding the inverse of a matrix by transforming [A|I] to  $[I|A^{-1}]$  using elementary row operations.

## **Practice Problems.**

1. Consider the vectors

$$\mathbf{u} = \begin{bmatrix} 1 \\ -1 \\ 0 \\ 2 \end{bmatrix} \quad \text{and} \quad \mathbf{v} = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 5 \end{bmatrix}$$

in  $\mathbb{R}^4$ . Find the following quantities:

- (i)  $\mathbf{u} \cdot \mathbf{v}$ ,  $\|\mathbf{u}\|$ ,  $\|\mathbf{v}\|$  and  $\|\mathbf{u} + \mathbf{v}\|$
- (ii) The unit vector in the direction of  $\mathbf{u} \mathbf{v}$ .
- (iii) The angle between  $\mathbf{u}$  and  $\mathbf{v}$ .
- (iv) The scalar t such that  $\mathbf{u}$  is orthogonal to  $\mathbf{u} + t\mathbf{v}$ .
- (v)  $proj_{\mathbf{u}}(\mathbf{v})$ , the orthogonal projection of  $\mathbf{v}$  onto  $\mathbf{u}$ .

Verify that the triangle and Cauchy-Schwarz inequalities hold for **u** and **v**.

2. Find the general solution of the linear system

$$\begin{cases} x + 3y + 2w = 2 \\ 2x + y + 5z + 4w = -16 \\ 2x + 3y + 3z = 4 \\ 3x + 11y - 2z + 11w = -1 \end{cases}$$

3. Let  $A = \begin{bmatrix} 1 & -x \\ 0 & -1 \end{bmatrix}$  and  $B = \begin{bmatrix} 1 & x \\ 5 & 2 \end{bmatrix}$ . Find x such that the product  $A^{-1}B^T$  is a symmetric matrix.

4. Let

$$A = \begin{bmatrix} 1 & -2 & 4 \\ 1 & 0 & 5 \\ 0 & 3 & 1 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 2 & -1 & 9 \\ 1 & 0 & 5 \\ 1 & -2 & 4 \end{bmatrix}.$$

- (i) Explain how *B* can be obtained from *A* by applying two elementary row operations.
- (ii) Find elementary matrices  $E_1$  and  $E_2$  such that  $B = E_2 E_1 A$ .

5. Consider the linear system

$$\begin{cases} 2x + 3y &= 4\\ x - 2y - z &= 0\\ 2x &- z &= 1 \end{cases}$$

- (i) Write this system as A**x** = **b** by introducing the matrices A, **x** and **b**.
- (ii) Compute the inverse  $A^{-1}$  by applying elementary row operations and use it to find the solution  $\mathbf{x} = A^{-1}\mathbf{b}$ .

## 6. True or false?

- Every system of 2 linear equations in 3 unknowns has infinitely many solutions.
- A  $5 \times 7$  matrix in row echelon form can have up to 7 leading 1's.
- There are vectors  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4$  in  $\mathbb{R}^3$  such that span $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4\} = \mathbb{R}^3$ .
- For any  $m \times n$  matrix A, the product  $AA^T$  is defined and symmetric.